EAST Search History

Ref	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
Ll	158	703/7.ccor.	US-PGPUB; USPAT	OR	ON	2006/09/01 14:24
L2	356	703/6.ccor.	ÙS-PGPUB; USPAT	OR	ON	2006/09/01 14:26
L3	207	703/11.ccor.	US-PGPUB; USPAT	OR	ON	2006/09/01 14:27
L4	2	(("5748767") or ("5769092")).PN.	US-PGPUB; USPAT	OR	OFF	2006/09/01 15:57
L5	4654	(orthopedic orthopaedic) and image	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2006/09/01 16:51
L13	1188	5 and (planning plan planner)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2006/09/01 17:08
L14	704	13 and anatom\$5	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2006/09/01 17:09
L15	4	14 and artifical	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2006/09/01 17:09
L16	357	14 and fixat\$4	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2006/09/01 17:11
L17	252	16 and element	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2006/09/01 17:13
L18	92	17 and simulat\$4	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2006/09/01 17:13
L19	3803	pre adj operati\$2	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2006/09/01 17:14
L20	26	18 and 19	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2006/09/01 17:14
L21	20	20 and @ad<="20030826"	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2006/09/01 17:15
L22	19	("4341220" "4905148" "5007936" "5086401" "5141512" "5242455" "5251127" "5299288" "5305203" "5360446" "5383454" "5389101" "5408409" "5517990" "5682886" "5733338" "5880976" "5995738" "6002859").PN.	US-PGPUB; USPAT; USOCR	OR	ON	2006/09/01 19:12
L23	19	("6205411").URPN.	USPAT	OR	ON	2006/09/01 19:19

		Results
7.	((((((pub-date > 1959 and pub-date < 2004 and FULL-TEXT((orthopedic or orthopaedic)) and FULL-TEXT(image)) and plan!) and pre operati!) and anatom!) and fixat!) and element) and artificial [All Sources(- All Sciences -)]	15
6.	(((((pub-date > 1959 and pub-date < 2004 and FULL-TEXT((orthopedic or orthopaedic)) and FULL-TEXT(image)) and plan!) and pre operati!) and anatom!) and fixat!) and element [All Sources(- All Sciences -)]	35
5.	((((pub-date > 1959 and pub-date < 2004 and FULL-TEXT((orthopedic or orthopaedic)) and FULL-TEXT(image)) and plan!) and pre operati!) and anatom!) and fixat! [All Sources(- All Sciences -)]	72
4.	(((pub-date > 1959 and pub-date < 2004 and FULL-TEXT((orthopedic or orthopaedic)) and FULL-TEXT(image)) and plan!) and pre operati!) and anatom! [All Sources(- All Sciences -)]	143
3.	((pub-date > 1959 and pub-date < 2004 and FULL-TEXT((orthopedic or orthopaedic)) and FULL-TEXT(image)) and plan!) and pre operati! [All Sources(- All Sciences -)]	211
2.	(pub-date > 1959 and pub-date < 2004 and FULL-TEXT((orthopedic or orthopaedic)) and FULL-TEXT(image)) and plan! [All Sources(- All Sciences -)]	4532
1.	pub-date > 1959 and pub-date < 2004 and FULL-TEXT((orthopedic or orthopaedic)) and FULL-TEXT(image) [All Sources(- All Sciences -)]	8127

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Recei	nt Search Queries	Results
<u>#1</u>	(((orthopedic <or>orthopaedic)<and>image)<and>anatom*) <and> (pyr >= 1951 <and> pyr <= 2003)</and></and></and></and></or>	257
<u>#2</u>	(((orthopedic <or>orthopaedic)<and>image<and>plan*) <and>and>anatom*) <and> (pyr >= 1951 <and> pyr <= 2003)</and></and></and></and></and></or>	221
<u>#3</u>	(((orthopedic <or>orthopaedic)<and>image<and>plan*) <and>and>anatom*<and>fixat*) <and> (pyr >= 1951 <and> pyr <= 2003)</and></and></and></and></and></and></or>	51
<u>#4</u>	(((orthopedic <or>orthopaedic)<and>image<and>plan*) <and>and>anatom*<and>fixat*<and>artificial) <and> (pyr >= 1951 <and> pyr <= 2003)</and></and></and></and></and></and></and></or>	23
<u>#5</u>	(((orthopedic <or>orthopaedic)<and>image<and>plan*) <and>and>anatom*<and>fixat*<and>artificial<and>element) <and> (pyr >= 1951 <and> pyr <= 2003)</and></and></and></and></and></and></and></and></or>	18



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<u>Development and Validation of a Navigational.. - Simon, Jaramaz.. (1997) (Correct) (2 citations)</u>
2 B. Colgan 1 T. Kanade 2 1 Center for **Orthopaedic** Research, Shadyside Hospital Pittsburgh, PA
HipNav includes three components: a **pre-operative planner**, a range of motion simulator, and an surgery. HipNav includes three components: a **pre-operative planner**, a range of motion simulator, and an www.ri.cmu.edu/pub_files/pub2/simon_david_1997_1/simon_david_1997_1.ps.gz

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An Overview of Medical Image Registration Methods - Maintz, Viergever (1996) (Correct) (1 citation) T. Kanade. Accuracy validation in image-guided **orthopaedic** surgery. InMedical robotics and computer 3. Liver d. Pelvis and perineum e. Limbs (**orthopedic**) 1. General 2. Femur 3. Humerus 4. Hand f. settings, but prominently so in the area of **planning**, consummation, and evaluation of surgical and www.cs.uu.nl/people/twan/personal/brussel_bvz.pdf

Towards More Capable and Less Invasive Robotic.. - O'Toole, III.. (1995) (Correct) (1 citation)
Capable and Less Invasive Robotic Surgery in Orthopaedics R.V. O'Toole III 12 D.A. Simon 2 B.
H.W. Staudte, and G. Rau. Computer assisted orthopedic surgery by means of individual templates surgical robots and computer-based pre-operative planning and simulation in orthopaedics. Figure 1
www.ri.cmu.edu/pub_files/pub2/o_toole_r_1995_1/o_toole_r_1995_1.ps.gz

Image Guided Orthopaedic Surgery Design and Analysis - Phillips, Viant, Mohsen.. (1996) (Correct) (1 citation) Image Guided Orthopaedic Surgery Design and Analysis R. Phillips* (CAOS) which takes an image guided approach to planning and implementing a trajectory, to assist an This instrument utilises the standard pre-operative and intraoperative imaging modality as its www.enc.hull.ac.uk/CAOS/doc/accimc95.ps.gz

Towards Computer-Assisted Surgery in Shoulder Joint.. - Valstar, Botha, van.. (Correct)

CJ Delft, The Netherlands b Department of **Orthopaedics**, Leiden University Medical Center, P.O. Box research programme focuses on the **pre-operative planning** and per-operative guidance issues. The ultimate part of this research programme focuses on the **pre-operative planning** and per-operative guidance issues. www.ph.tn.tudelft.nl/People/albert/papers/PRS Valstar.pdf

A Visualisation Platform for Shoulder Replacement Surgery - Botha, Post (2001) (Correct) groups of the Delft Technical University, the **Orthopaedics** Department of the Leiden University Medical (without loss of domain-specific benefits) and the **planned** integration of predictive modelling. 1 on per-operative assistance with very little **pre-operative planning** facilities and almost no predictive www.ph.tn.tudelft.nl/People/albert/papers/botha2001.pdf

Study Report - Neuro-Endoscopic Manipulator - Draft Th April (Correct)

the required task. This has been translated to **orthopaedic** surgery by measuring a control force and using Experiment Apparatus and Materials Project **Planning** References Introduction This report discusses which is guided to the site with the aid of **pre-operative** MR images. The site is identified by www.me.ic.ac.uk/case/mim/people/steve/../../projects/roboscope/Study_Report.pdf

Medical Imaging, Visualization and Registration in.. - David Simon Ph (Correct) execution of surgical procedures are providing **orthopaedic** surgeons with a powerful new set of tools for and G. Rau. A compact robot for image guided **orthopedic** surgery: Concept and preliminary results. In which are being introduced to aid in the **planning** and execution of surgical procedures are www.cs.cmu.edu/afs/cs/user/das/ftp/CORR.ps.gz

Frameworks for Evaluating Accuracy in CAOS - Simon Ph Center (1997) (Correct) in CAOS D.A. Simon, Ph.D. 1,2 1 Center for **Orthopaedic** Research, Shadyside Hospital, Pittsburgh, PA, intra-operative guidance or robot motion **planning** is performed to enable the surgical action which

the components of a typical CAOS system. **Pre-operatively**, patient-specific medical images are www.ri.cmu.edu/pub_files/pub1/simon_david_1997_4/simon_david_1997_4.pdf

Simulation, Planning, and Execution of Computer-Assisted Surgery - Takeo Kanade Pi (1996) (Correct) surgery, one of the most common procedures in **orthopaedic** surgery, is targeted because of the Simulation, **Planning**, and Execution of Computer-Assisted Surgery Registration. As discussed above, the **preoperative** surgical simulations aid in seeking an optimal www.ri.cmu.edu/pub_files/pub2/kanade_takeo_1996_1/kanade_takeo_1996_1.ps.gz

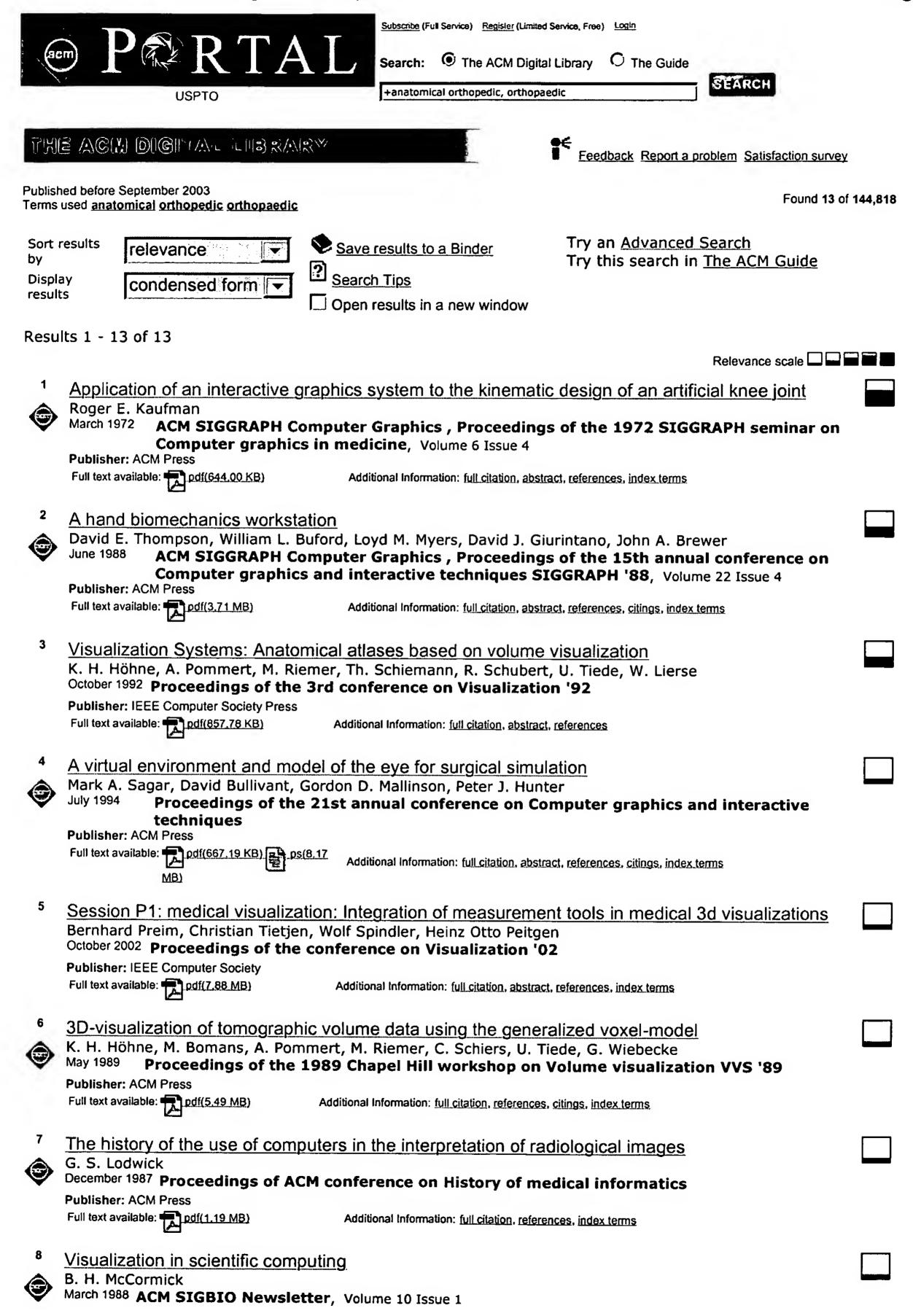
A Stereotactic/Robotic System for Pedicle Screw Placement - Santos-Munné, Peshkin, al. (1995) (Correct) S. David Stulberg Thomas C. Kienzle III Dept. of Orthopaedic Surgery Northwestern U. Medical School use of two-dimensional images for preoperative planning. During the planning stage, the surgeon becomes is the use of two-dimensional images for preoperative planning. During the planning stage, the othello.mech.nwu.edu/~peshkin/papers/PedicleScrew/PedicleScrew.ps

Design and Evaluation of 3-D . . . - Blackwell, al. (1996) (Correct)

1 Robotics Institute 2 Center for **Orthopaedic** Research Carnegie Mellon University Shadyside the user interface components of a **pre-operative planning** system for performing complex 3-D spatial evaluating the user interface components of a **pre-operative planning** system for performing complex 3-D reports-archive.adm.cs.cmu.edu/anon/robotics/CMU-RI-TR-96-44.ps

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